

# Super Gripper IVANKO

Force required to close gripper

## SET LISTING

Positions		Force in lbs
1	3	45.00
1	4	56.41
1	5	69.58
1	6	84.50
1	7	101.17
1	8	119.60
1	9	139.78
1	10	161.71
1	11	185.40
1	12	210.84
2	4	64.32
2	5	77.49
2	6	92.41
2	7	109.08
2	8	127.51
2	9	147.69
2	10	169.62
2	11	193.30
2	12	218.74
3	1	45.00
3	5	87.15
3	6	102.07
3	7	118.74
3	8	137.17
3	9	157.35
3	10	179.28
3	11	202.96
3	12	228.40
4	1	56.41
4	2	64.32
4	6	113.48
4	7	130.15
4	8	148.58
4	9	168.76
4	10	190.69
4	11	214.38
4	12	239.82
5	1	69.58
5	2	77.49
5	3	87.15
5	7	143.32
5	8	161.75
5	9	181.93
5	10	203.86
5	11	227.54
5	12	252.98
6	1	84.50
6	2	92.41
6	3	102.07
6	4	113.48
6	8	176.67
6	9	196.84
6	10	218.78
6	11	242.46
6	12	267.90

Positions		Force in lbs
7	1	101.17
7	2	109.08
7	3	118.74
7	4	130.15
7	5	143.32
7	9	213.52
7	10	235.45
7	11	259.14
7	12	284.58
8	1	119.60
8	2	127.51
8	3	137.17
8	4	148.58
8	5	161.75
8	6	176.67
8	10	253.88
8	11	277.56
8	12	303.00
9	1	139.78
9	2	147.69
9	3	157.35
9	4	168.76
9	5	181.93
9	6	196.84
9	7	213.52
9	11	297.74
9	12	323.18
10	1	161.71
10	2	169.62
10	3	179.28
10	4	190.69
10	5	203.86
10	6	218.78
10	7	235.45
10	8	253.88
10	12	345.11
11	1	185.40
11	2	193.30
11	3	202.96
11	4	214.38
11	5	227.54
11	6	242.46
11	7	259.14
11	8	277.56
11	9	297.74
12	1	210.84
12	2	218.74
12	3	228.40
12	4	239.82
12	5	252.98
12	6	267.90
12	7	284.58
12	8	303.00
12	9	323.18
12	10	345.11

## SORTED

Positions		Force in lbs
3	1	45.00
4	1	56.41
4	2	64.32
5	1	69.58
5	2	77.49
6	1	84.50
5	3	87.15
6	2	92.41
7	1	101.17
6	3	102.07
7	2	109.08
6	4	113.48
7	3	118.74
8	1	119.60
8	2	127.51
7	4	130.15
8	3	137.17
9	1	139.78
7	5	143.32
9	2	147.69
8	4	148.58
9	3	157.35
1	10	161.71
8	5	161.75
9	4	168.76
2	10	169.62
8	6	176.67
3	10	179.28
9	5	181.93
11	1	185.40
4	10	190.69
2	11	193.30
9	6	196.84
3	11	202.96
5	10	203.86
12	1	210.84
9	7	213.52
4	11	214.38
2	12	218.74
6	10	218.78
5	11	227.54
3	12	228.40
7	10	235.45
4	12	239.82
6	11	242.46
5	12	252.98
8	10	253.88
7	11	259.14
6	12	267.90
8	11	277.56
7	12	284.58
9	11	297.74
8	12	303.00
9	12	323.18
12	10	345.11

COC =

T= 100

1= 140

2= 195

3= 280

4= 360